

Figure 1A

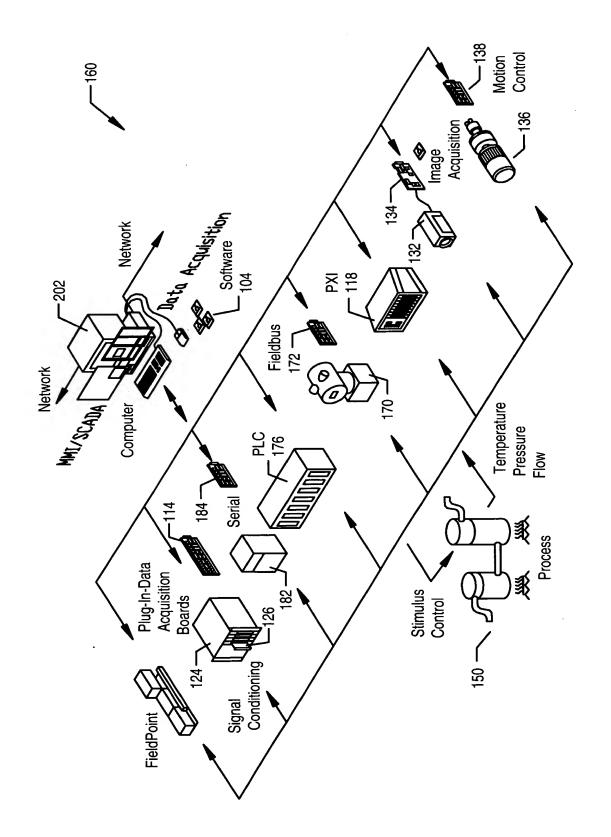


Figure 1B

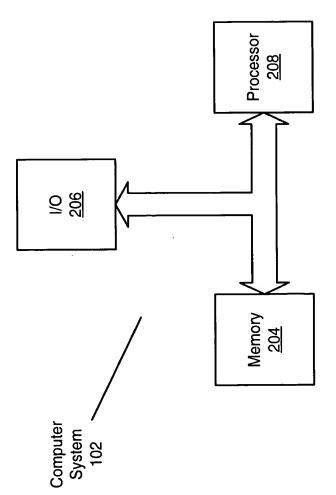
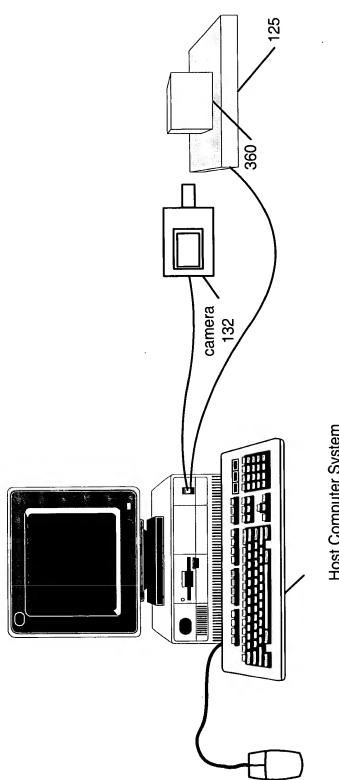


Figure 2



Host Computer System 102A

Figure 3A

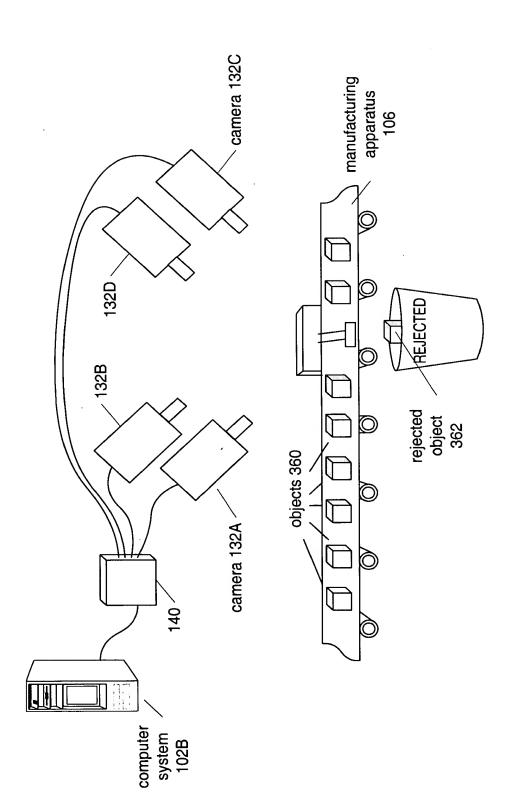


Figure 3B

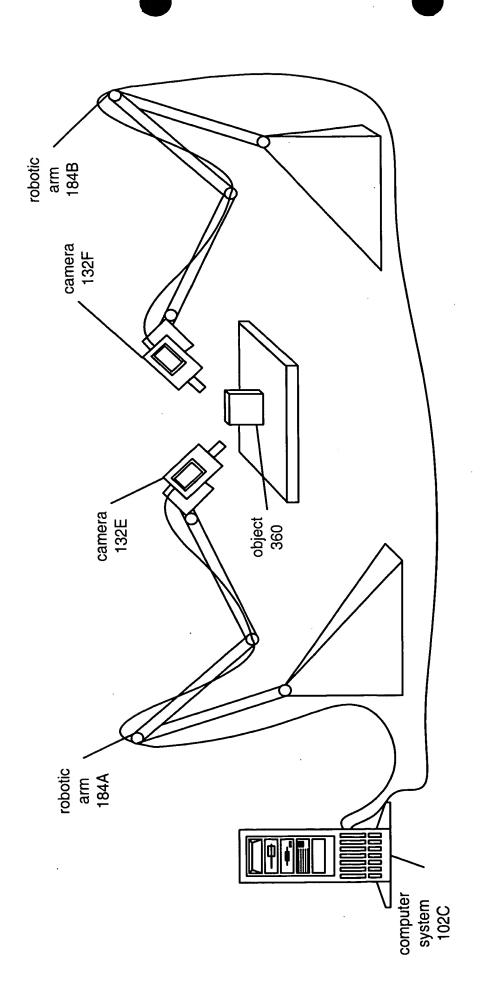


Figure 3C

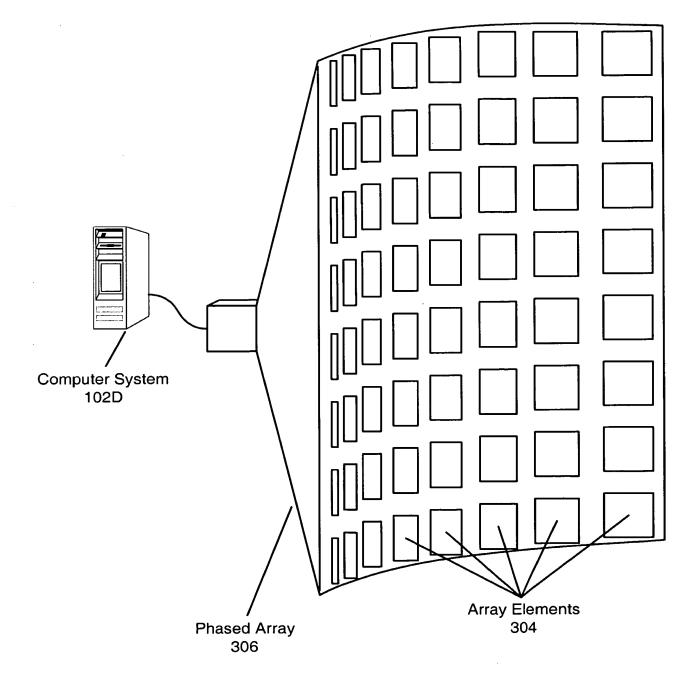


Figure 3D

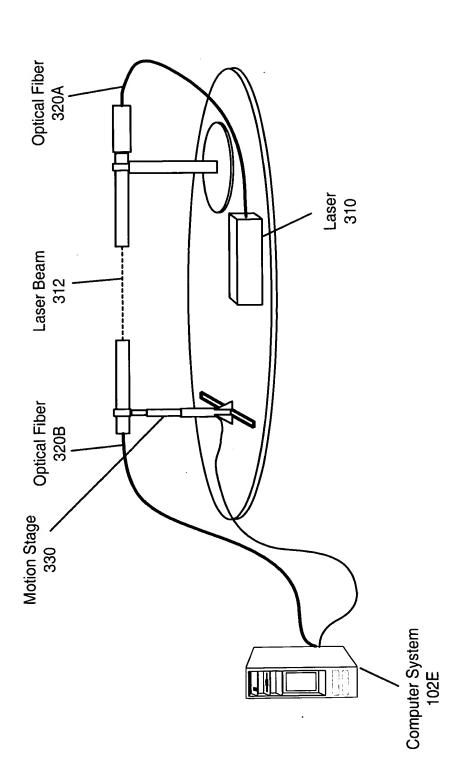
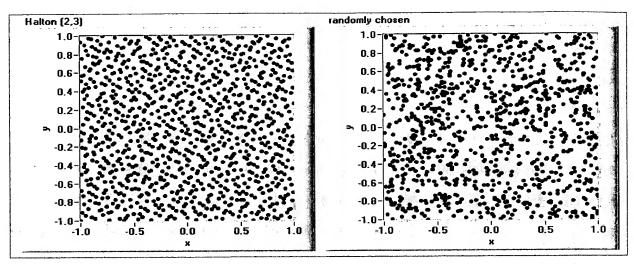
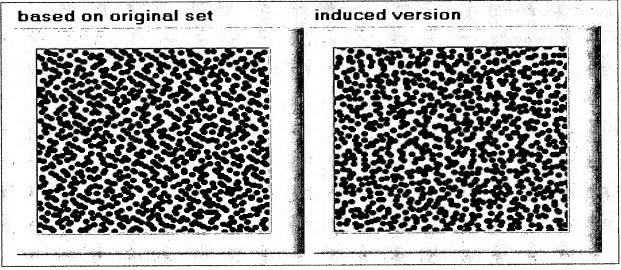


Figure 3E



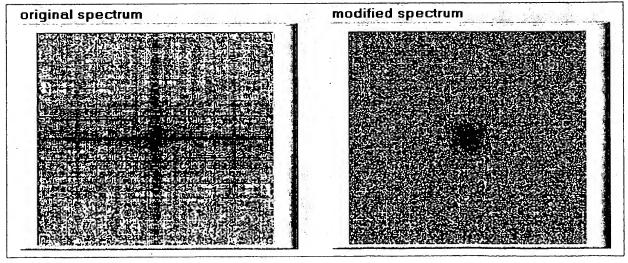
The first 1000 Halton points (left) and randomly chosen points (right)

Figure 4A



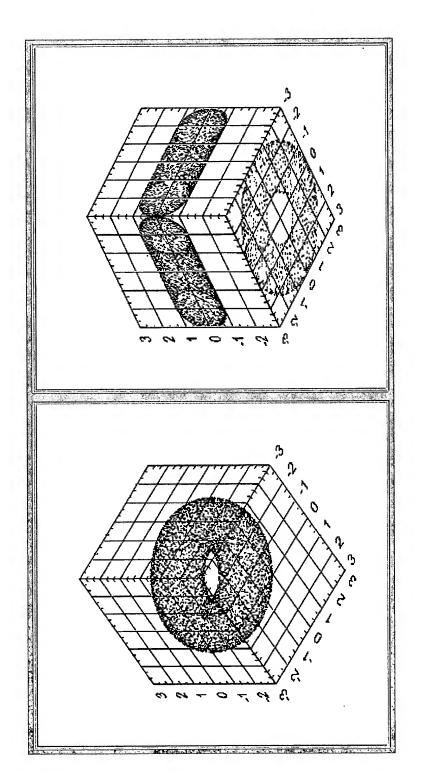
Original LDS (left) and induced LDS (right)

Figure 4B



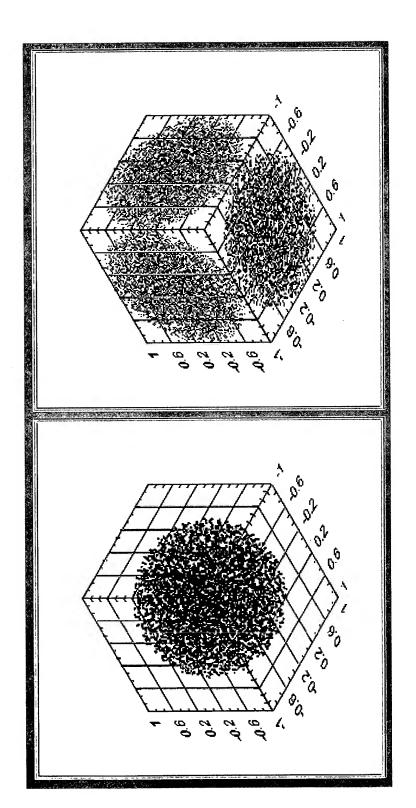
Fourier transforms of original LDS (left) and induced LDS (right)

Figure 4C



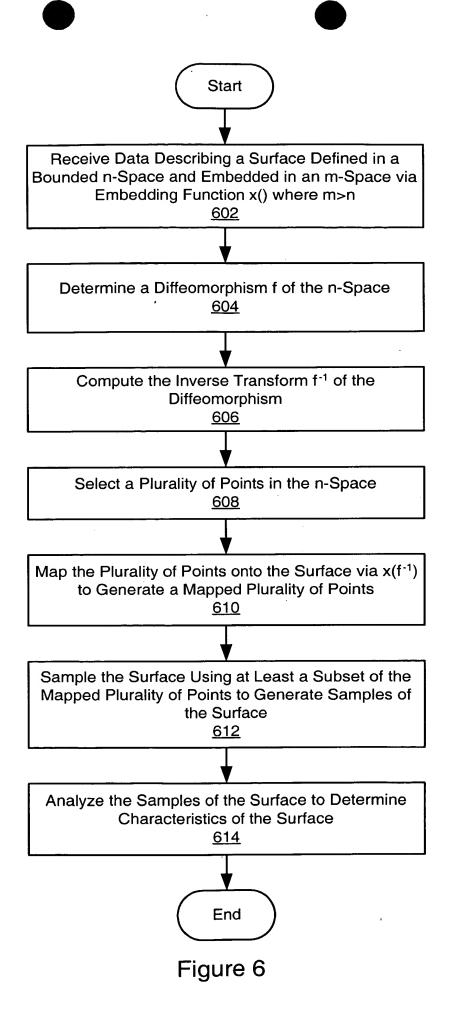
Well-distributed point set on the surface of a torus (left) and projections (right)

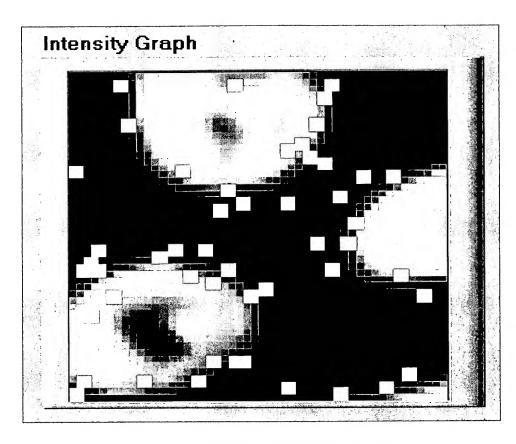
Figure 5A



Well-distributed point set in a unit ball (left) and projections (right)

Figure 5B





Edge Detection in an Image

Figure 7

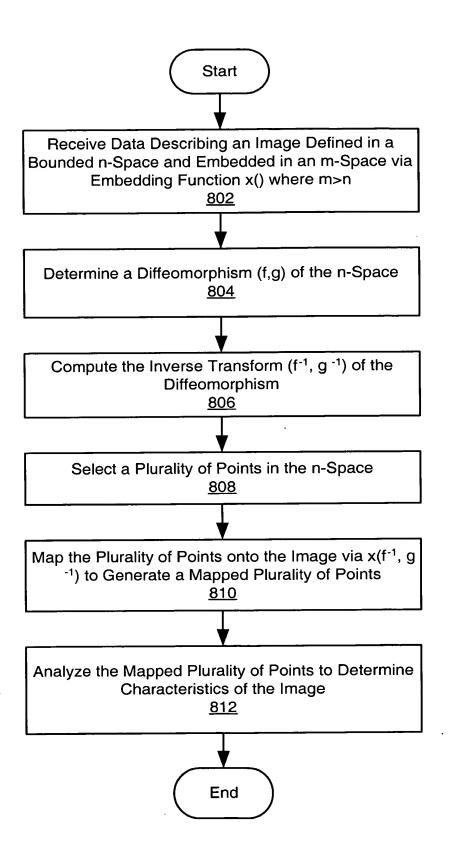
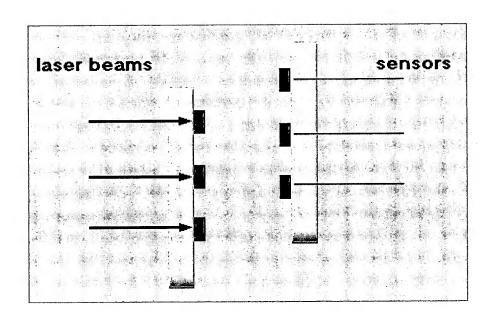


Figure 8



Simplified model of alignment problem in fiber optics

Figure 9